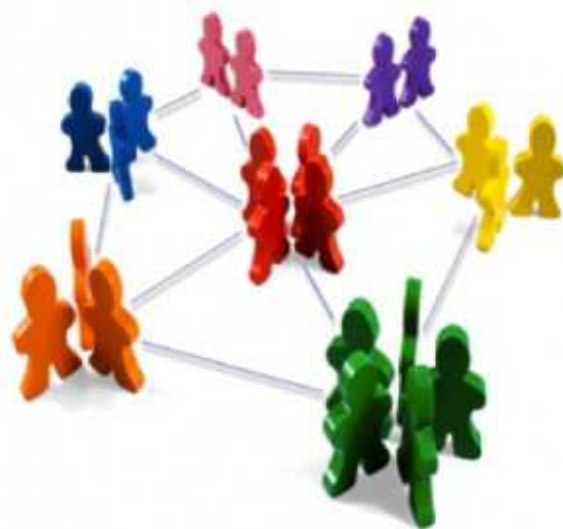


Quick Start Instructions for the Community Detection Toolbox v. 0.9

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1 Installation

Installation of the CDTB is extremely simple. You can download the file CDTB.zip from <http://mathworks.com>. When the download is complete, unzip the file in a folder of your choice. From now on we will assume that it is the folder `c:\CDTB`. When unzipped, the folder will contain several subfolders, e.g., `c:\CDTB\Algorithms`, `c:\CDTB\Auxiliary` etc. Now you are ready to go.

2 A Simple Demo

Start Matlab, go to `c:\CDTB` and in the command line type

```
>> PathAdd
```

and hit [Enter]. This will add to the *Matlab Path* the subdirectories which contain the Matlab *.m files which do the actual community detection work¹. In the command line type

```
>> CDTBDemo01
```

and hit [Enter]. The *Matlab script* CDTBDemo01.m will run and in the command window you will get a message which says

```
The NMI metric between V0 and Vest is 1
```

NMI is the *normalized mutual information* index of partition (i.e., clustering) similarity. It takes values in the interval [0,1]. The maximum value 1 indicates maximum similarity, i.e., identity. The partitions compared are V_0 , the true partition, and V_{est} , the partition estimated by a *modularity maximization algorithm*. Hence in this experiment V_{est} is identical to V_0 . This can also be seen in the plot which Matlab presented. It looks like this

¹ Note that the new path is not saved, so you must retype PathAdd every time you start a new Matlab session. Or, you can go to the Matlab menu File/Set Path and click the button Save, which will make Matlab memorize the path for all future sessions.

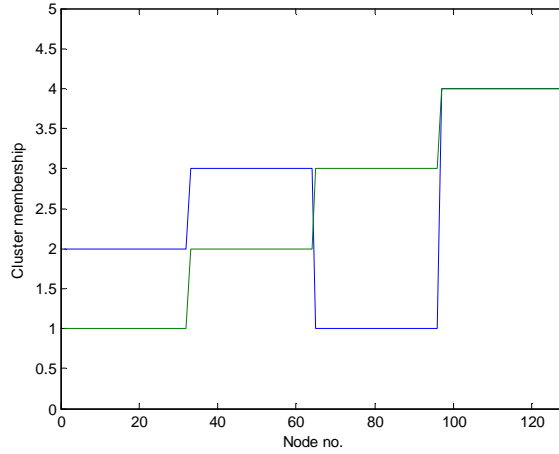


Figure 2.1

The horizontal axis gives the node id. numbers. The demo utilized a *Girvan-Newman* graph [NewmanGirvan2004] with 128 nodes. These nodes originally were partitioned (by their edge patterns) into four *communities* (i.e., clusters) as follows: nodes 1, 2, ..., 32 go into community no.1, nodes 33, 34, ..., 64 go into community no.2 and so on; this partition is V_0 and is plotted by the green line in Fig.1. V_{est} , on the other hand, assigns nodes 1, 2, ..., 32 to community no.2, nodes 33, 34, ..., 64 to community no.3 and so on. While the community *labels* are different between V_0 and V_{est} , the actual division into clusters is the same. In short, the modularity maximization algorithm obtained the correct solution, modulo a relabeling of clusters.

3 The GUI

Let us also run a simple demo of the Graphical User Interface (GUI). In the Matlab command line type

```
>> gui
```

and hit [Enter]. You will get the following standard Matlab GUI.

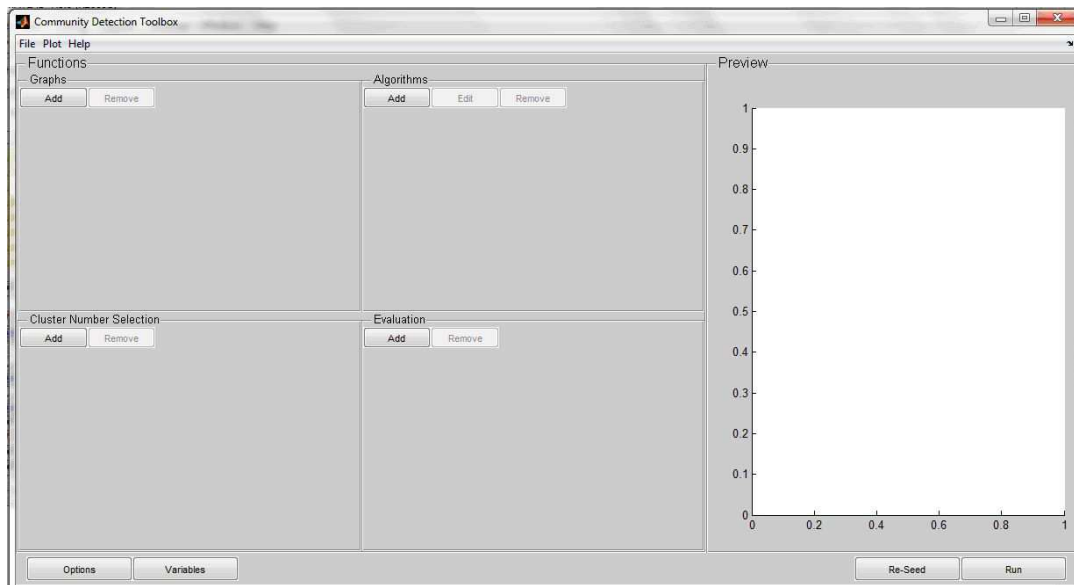


Figure 2.2

The GUI, makes it easy to design and perform community detection experiments. To perform exactly the same experiment that CDTBDemo01 performed, do the following. Go to the GUI menu File/Import Data. A standard *File Dialog* will open, like this

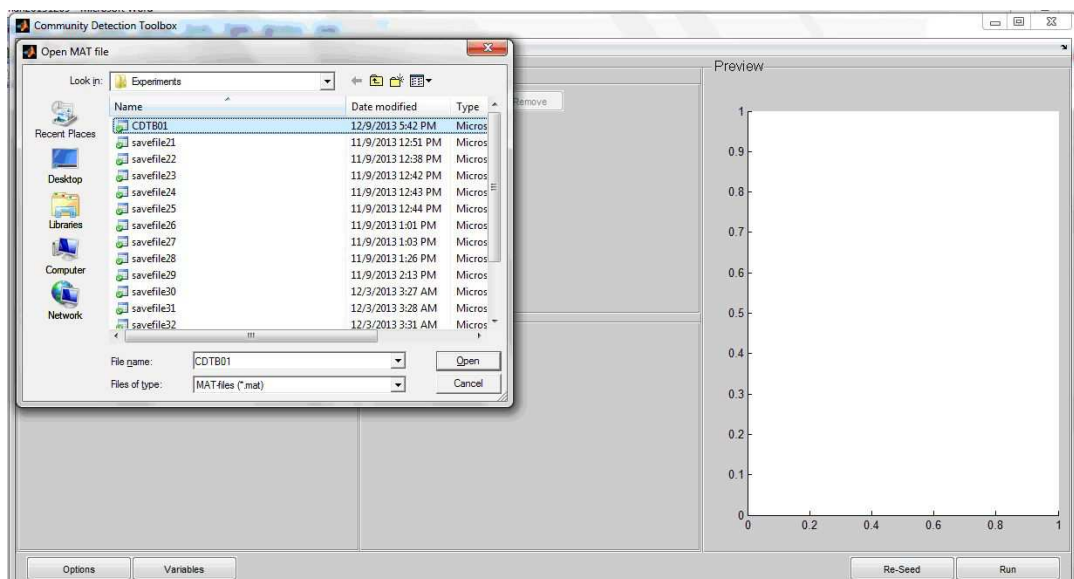


Figure 2.3

Select the file CDTB01 and click on the Open button. The GUI will change and now look like this:

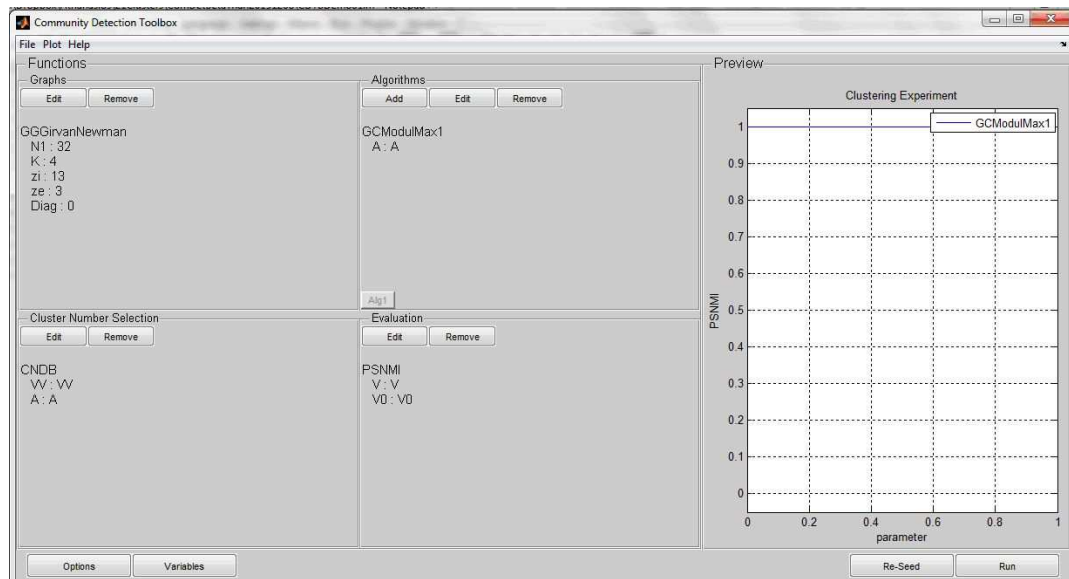


Figure 2.4

Now click on the Run button. A *progress bar* will flash for a while and then you will get a plot (actually a straight line). The GUI has run the experiment specified by the choices appearing in Fig. 2.4. You can access these results by selecting the menu option Plot/Results to CLI: if you switch to the Matlab command line (it is always available, e.g. by [Alt]-[Tab]-ing) you will see that a new variable has been loaded in your *Matlab workspace*, called `Results`. We will later discuss which results are contained in `Results`. We can now take a break.